Verifying Multiparty Call in ATM UNI Signalling Protocol

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Abstract: - This paper presents formal specification and verification of the multiparty call in ATM UNI signalling protocol. The protocol specification is written in the CCS process algebra (Calculus of Communicating Systems). Verification is done by using the NCSU-Concurrency Workbench. Due to the complexity of the protocol, the model is decomposed into three components. The protocol is verified by the model-checking feature of the Workbench. Each of its components is checked for safety and liveness properties using temporal CTL (Computation Tree Logic) and modal mu-calculus logic.

Key-Words: - formal specification, model checking, verification, ATM signalling protocol, process algebra

1 Introduction
A typical protocol development process involves two phases: the specification and design phase in which a high level design of the protocol is specified using a partially formal protocol description language and an implementation phase in which the high level description of the protocol is translated to an implementation which is tested extensively for bugs. The bugs in the final implementation could appear either because of implementation errors or design errors. Implementation errors can be found easily. Design errors, however, are not only subtle and hard to trace, but also quite expensive to correct as they require going back to the design phase. Therefore, it is necessary to apply techniques that detect errors early in the design phase. One solution to this problem is to use rigorous formal methods in the design process.

This paper presents formal specification and verification of the multiparty call in ATM UNI signalling protocol. The protocol specification is written in the CCS process algebra (Calculus of Communicating Systems). Verification is done by the NCSU-Concurrency Workbench [4, 5].

The model of the protocol includes the specification of the procedures for point-to-multipoint connections and model includes three users: one calling and two called users. Two users enjoy the same rights: both can initiate the basic call (point-to-point) and have of a third party join the call.

Due to the complexity of the protocol, the model is decomposed [8-10] into three components. The first one covers all procedures for point-to-point call. The second includes the procedures for a point-to-multipoint connection with clearing point-to-point connection. In that case, after setting up a point-to-point connection, only one additional user can be added to the connection. These two components represent two possible “flows” of the protocol, because after establishing a point-to-point connection, it is possible either to release a point-to-point call or to connect a new party to it. The third component consists of the procedures for a point-to-point and a point-to-multipoint connection with a restriction to one passive user. A passive user can only be a called user. The third component includes one calling, one called and one added user. Thus, the relations between the first two components are checked: the procedures of releasing a point-to-point call with the procedures for connecting and
disconnecting an added user.

The protocol is verified by using the model-checking feature of the Workbench. Each component of the protocol is checked for safety and liveness properties using the temporal CTL (Computation Tree Logic) and the modal mu-calculus logic.

The paper is organised in the following way. Informal description of the model, model architecture and message flows for successful establishing and clearing of a multiparty call are presented in Section 2. Formalization of the protocol, components of the model as well as model assumptions are described in Section 3. Decomposition of the protocol and verification results are reported in Section 4. Conclusions are given in Section 5.

2 Model Description

The procedures for establishing and clearing of a multiparty call are defined by the User-Network Interface (UNI 3.1) signalling protocol [1]. It is assumed that there are three users or ATM end-stations, each connected to the ATM network through a user network interface (UNI). Two users participate in a point-to-point call and a third one can join the connection at the request of the calling (root) user (Figure 1). The UNI has two components: one defines the control procedures for the user side (USI) and the other defines the control procedures for the network side (NSI). The USI and the NSI are assumed to be connected by means of a reliable network and that the underlying ATM network is also reliable and error-free.

A multiparty call is set up by first establishing a point-to-point connection between a calling and a called user. After this set up is complete, an additional user (party) can be added to the connection by an ADD_PARTY request from the calling user. A party may be connected to or disconnected from a multiparty call at any time after the connection is established. A party can be added to an existing point–to-point connection only via the calling user who issues an ADD_PARTY message, or be dropped from a connection at the request of either the calling user or himself (but not by the other user).

A typical execution sequence for a successful addition of a third party to an already existing (point-to-point) call is as follows (Figure 2).

The term User refers to the combination of a local user and the USI. A calling user initiates the addition of a new user (party) and sends an ADD_PARTY request to the NSI. Index 1 refers to a calling side, index 2 to a called side and index 3 to a added (party) side. The NSI forwards the request across the network and sends a CALL_PROCEEDING message back to the calling user. When the NSI (party side) receives the request, it forwards the request to the party as a SETUP message. If the party responds with a CONNECT message, the NSI responds with a CONNECT_ACKNOWLEDGE message and sends a CONNECT message to the NSI. The NSI then sends an ADD_PARTY_ACKNOWLEDGE message to the calling user. When the calling user receives this message, the multiparty call is established.

An execution sequence for dropping of a party from an existing multiparty call by the calling user is as follows (Figure 3).

The calling user indicates dropping of a party out by sending a DROP_PARTY message, which is forwarded by the NSI to the NSI. The NSI sends a RELEASE message to the party. The party responds
with a RELEASE_COMPLETE message and when the calling user receives the DROP_PARTY_ ACKNOWLEDGE message, the clearing of the party is done.

Fig. 3: Message flow for dropping of a party out

3 Formal Description

Formal model of establishing and clearing of a multiparty call is written in the process algebra CCS (Calculus of Communicating Systems) [2, 3]. The terms in it are described by the following grammar (1).

\[
P :: = \text{nil} \mid \alpha P \mid (P + P) \mid (P \mid P) \mid P[f] \mid P \setminus L \mid \text{proc } C = P
\]

(1)

“\(\cdot\)” represents the prefixing operator; “\(+\)” is the summation of choice operator; “\(\mid\)” is the parallel composition operator; “\(f\)” is a relabelling function; “\(\setminus\)” is the restriction operator, and “\(\text{proc } C\)” is used for defining a processes.

The model consists of 13 processes or components which are executed simultaneously; therefore they are connected by a parallel composition operator. The model is added to the model for establishing and clearing a point-to-point call [7]. Given that only a calling user can add a party to the call, the model of a multiparty call must distinguish a calling and a called user. In this case, the model consists of three users. Two users have the same rights and both of them can initiate the point-to-point call and then can realise the multiparty call. A third user is a party user and can be only an added user. Thus, after establishing a point-to-point call, a calling user can either clear the call or initiate the procedures for establishing the multiparty call. If a calling user clears a point-to-point call, the model returns to the starting state. In the other hand, after having added a party to the call, either a calling or an added user can disconnect a party.

To establish a multiparty call, the model must have the following components:

1. the models of the local party, local calling and local called user,
2. the models of the USI on the party side, calling side and called side,
3. the models of the NSI on the party side, calling side and called side,
4. the models of UNI channels (between USI and NSI) on the party side, calling side and called side, and the network channels.

The components (models) of the calling and called side are equal these users having the same rights.

The model includes the following simplifying assumptions:

1. The channels are formalized as one-place buffers and all of them are reliable and error-free,
2. The contents (information elements) of a message are ignored,
3. The model includes point-to-point and point-to-multipoint calls, multipoint-to-multipoint calls are not considered and “calls” and “connections” are equivalent,
4. The model does not include timeouts and retransmissions.

4 Protocol Verification

This section presents some verification results. Verification is based on two important properties of the protocol: freedom from the deadlock and liveness. The first property is checked for the safety of the protocol. Checking of the second one proves that if nothing bad happens, a connection will be eventually established. The properties are verified using the model-checking feature in the Concurrency Workbench.

4.1 Model Decomposition

Due to complexity of the protocol, the model is decomposed into the following three components:

1. procedures for establishing and clearing of a point-to-point call,
2. procedures for establishing of a point-to-point call with the procedures for adding and dropping of a party,
3. procedures for establishing and clearing of a multiparty call with a restriction to one passive user in a point-to-point call.

The reason for protocol decomposition is a lack of memory and time wastage, given that over 40000
Decomposition of the model will be presented by messages which are important in particular components (key messages). The model for establishing and clearing of a multiparty call with the corresponding messages is shown in Figure 4.

There are two users that can establish (SETUP) a point-to-point call and clear (RELEASE) point-to-point call. A party is not included.

The second component includes the procedures for establishing and clearing of a multiparty call without clearing a point-to-point connection (Figure 6). In that case, after setting up a point-to-point connection, only a party user can be added to the connection. These two components represent two possible “flows” of the protocol, because after establishing a point-to-point connection, it is possible either to release a point-to-point call or to add a party to the connection.
4.2 Model Checking

The properties (deadlock and liveness) are specified in a temporal logic, known as the modal mu-calculus [6]. The syntax of mu-calculus is given by the following grammar (2):

\[
\Phi ::= \text{tt} \mid \text{ff} \mid X \mid \neg \Phi \mid \Phi \lor \Phi \mid \Phi \land \Phi \mid <\alpha>\Phi \mid [\alpha]\Phi \mid \nu X.\Phi \mid \mu X.\Phi 
\]

(2)

The formula \text{tt} holds of every state, whereas the formula \text{ff} holds of no state. The formula \(\Phi_1 \lor \Phi_2\) holds of a state if either \(\Phi_1\) or \(\Phi_2\) hold of the state; likewise \(\Phi_1 \land \Phi_2\) holds of a state if both \(\Phi_1\) and \(\Phi_2\) hold of the state. \(\alpha\) refers to actions. \(<\alpha>\) and \([\alpha]\) are referred to as path modalities. The modal formula \(<\alpha>\Phi\) holds of a state if the state has some \(\alpha\)-derivative at which \(\Phi\) holds, and \([\alpha]\Phi\) holds at a state if all \(\alpha\)-derivatives of the state satisfy \(\Phi\). \(\nu\) represents the greatest fixpoint operator (max) and \(\mu\) represents the least fixpoint operator (min).

The mu-calculus is extended to include the CTL (Computation Tree Logic) operators [6]. The CTL formulas and corresponding mu-calculus translations that were used in the verification (3, 4):

\[
AG\ prop \ max X = prop \land [-\{}]X \tag{3}
\]

\[
A (prop_1 \lor prop_2), \ min X \ prop_2 \lor (prop_1 \land [-\{}]X \land \langle[-\{}]\rangle tt) \tag{4}
\]

Intuitively, \(A\) means that the property should hold for all computations, \(G\) means “always” and \(U\) means “until”.

Each component of the protocol is checked for safety (deadlock freedom) and liveness properties. The first property says that the protocol is free of deadlocks. The following mu-calculus formula expresses this property (5):

\[
can\_deadlock = \min X = [-\{}]\text{ff} \lor \langle[-\{}]\rangle \text{tt} \tag{5}
\]

The second property requires introducing some new visible actions in the model. These actions are used for checking of the model behaviour and the model progress as expected. The new models for the local \text{User}_1 and \text{User}_2 (these models are the same) and added \text{User}_3 are shown in Figure 8 and Figure 9. The visible actions are bolded.

Each component includes only its visible actions, characteristic for this component, which are interesting for checking. In this case, for each component some corresponding property is being checked. With respect to that, it is defined a macro (6) with parameters \(a\), \(p_1\) and \(p_2\) which says that on all paths after an action \(a\) eventually a state satisfying \(p_2\) occurs and until then every state satisfies \(p_1\).

\[
\text{proc NullUser}_1 = \ 'setup\_req', \ 'setup\_request', \ (\ 'setup\_conf', \ User_1, \ NullAddParty_1 \ + \ 'setup\_err', \ 'setup\_error', \ User_1) \ + \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ User_1, \ ActiveUser_1) \ + \ 'setup\_err1', \ 'setup\_error1', \ User_1) \\
\text{proc ActiveUser}_1 = \ 'rel\_ind', \ 'rel\_resp', \ 'rel\_req', \ 'release\_request', \ (\ 'rel\_conf', \ User_1, NullUser_1) \\
\text{proc NullAddParty}_1 = \ 'add\_req', \ 'add\_request', \ (\ 'add\_conf', \ User_1, \ add\_confirmation, \ ActiveAddParty_1 \ + \ 'add\_err', \ 'add\_error', \ NullAddParty_1) \ + \ 'rel\_req', \ 'release\_request', \ (\ 'rel\_conf', \ User_1, NullUser_1) \\
\text{proc ActiveAddParty}_1 = \ 'drop\_req', \ 'drop\_request', \ (\ 'drop\_conf', \ User_1, \ NullUser_1) \\
\text{proc PocDodKor}_3 = \ 'drop\_req', \ 'drop\_request', \ (\ 'rel\_req', \ 'rel\_resp', \ 'rel\_conf', \ 'release\_request', \ PocDodKor_3) \ + \ 'rel\_ind', \ 'rel\_resp', \ PocDodKor_3 \\
\text{Fig. 8: Model of a local user (User}_1 \text{ and User}_2) \\
\text{proc NullParty}_3 = \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ ActiveParty_3) \ + \ 'setup\_err', \ 'setup\_error', \ PocDodKor_3 \\
\text{proc ActiveParty}_3 = \ 'rel\_ind', \ 'rel\_resp', \ (\ 'rel\_req', \ 'release\_request', \ PocDodKor_3) \\
\text{Fig. 9: Model of a party (User}_3) \\
\text{prop liveness\_setup} = \ liveness (\ 'setup\_request', \ (\ 'setup\_error', \ 'setup\_error', \ (\ 'setup\_resp', \ 'setup\_response', \ (\ 'setup\_conf', \ User_1, \ NullAddParty_1) \ + \ 'setup\_err', \ 'setup\_error', \ NullUser_1) \ + \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ User_1, \ ActiveUser_1) \ + \ 'setup\_err1', \ 'setup\_error1', \ User_1) \\
\text{prop liveness\_release} = \ liveness (\ 'setup\_resp', \ (\ 'setup\_resp', \ 'setup\_error', \ (\ 'setup\_resp', \ 'setup\_response', \ (\ 'setup\_conf', \ User_1, \ NullAddParty_1) \ + \ 'setup\_err', \ 'setup\_error', \ NullUser_1) \ + \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ User_1, \ ActiveUser_1) \ + \ 'setup\_err1', \ 'setup\_error1', \ User_1) \\
\text{In the first component, a liveness of the procedures for establishing (7) and clearing (8) of a point-to-point call are checked.}
\]

\[
\text{prop liveness\_setup} = \ liveness (\ 'setup\_request', \ (\ 'setup\_error', \ 'setup\_error', \ (\ 'setup\_resp', \ 'setup\_response', \ (\ 'setup\_conf', \ User_1, \ NullAddParty_1) \ + \ 'setup\_err', \ 'setup\_error', \ NullUser_1) \ + \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ User_1, \ ActiveUser_1) \ + \ 'setup\_err1', \ 'setup\_error1', \ User_1) \\
\text{prop liveness\_release} = \ liveness (\ 'setup\_resp', \ (\ 'setup\_resp', \ 'setup\_error', \ (\ 'setup\_resp', \ 'setup\_response', \ (\ 'setup\_conf', \ User_1, \ NullAddParty_1) \ + \ 'setup\_err', \ 'setup\_error', \ NullUser_1) \ + \ 'setup\_ind', \ (\ 'setup\_resp', \ 'setup\_response', \ User_1, \ ActiveUser_1) \ + \ 'setup\_err1', \ 'setup\_error1', \ User_1) \\
\]

(7)
In the second component, liveness of the procedures for adding (9) and dropping (10) of a party and a liveness of the procedure for establishing of a point-to-point call (7) too are checked.

\[
\text{prop liveness\_add} = \\
\text{liveness (add\_request}_1, ([add\_error}_1]ff \land [setup\_error}_3]ff), <setup\_response>_tt) (9)
\]

\[
\text{prop liveness\_drop} = \\
\text{liveness (add\_confirmation}_1, ([add\_request}_1]ff U, <drop\_request>_tt \lor <release\_request>_tt) (10)
\]

In addition checking (7) and (8), the third component includes checking of liveness when a calling user can concomitantly add a party or release a point-to-point call (11) (interrelation between first two components).

\[
\text{prop liveness\_add\_release} = \\
\text{liveness (setup\_response}_2, ([add\_error}_1]ff \land [release\_request}_1]ff), <setup\_response>_tt) (11)
\]

For example, the formula (9) says that if after add\_request\_1 nothing bad happens (i.e. events add\_error\_1 and setup\_error\_3 do not occur), a setup\_response\_3 takes place.

For the last property the model had 8833 states and 30186 transitions. Verification of the properties took about 3 minutes on a SUN Ultra 1 workstation with 256 Mbytes of memory.

5 Conclusion

Formal specification and verification of the multiparty call in ATM UNI signalling protocol are reported. The specification is written in the CCS process algebra and verification is done by using model-checking feature of the Concurrency Workbench. Due to complexity of the protocol, the model is decomposed into three components and each is checked for safety and liveness properties using temporal logic CTL and modal mu-calculus logic.

In the protocol design, there was a constant interaction between the modelling and verification phases. Therefore, in reality, the border between these two phases is being lost.

Further studies would be a more detailed modelling including timeouts and retransmissions, modelling of more complex protocols with more users, possibility of negotiations and mobile agents.

References:


